

Low-rank time-frequency synthesis

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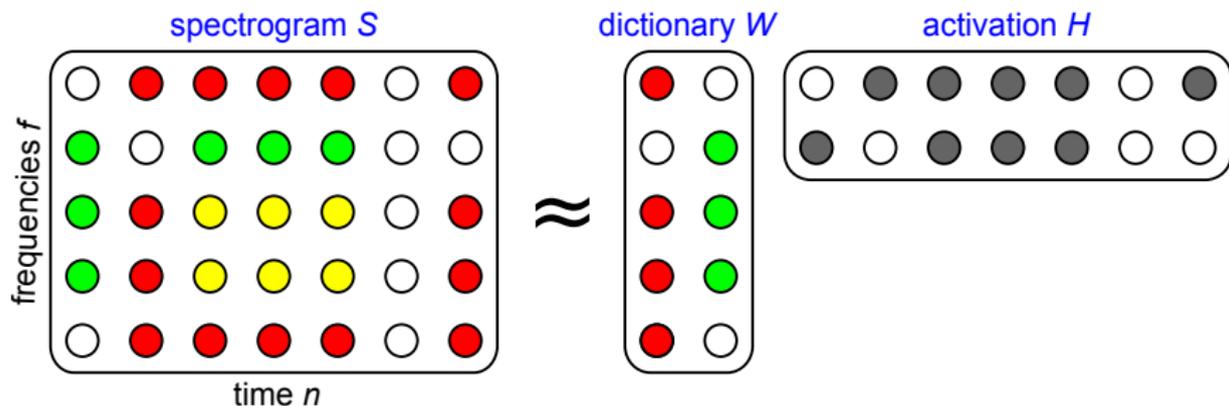
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Spectral unmixing by NMF



- ▶ $y_{fn} = \sum_t x(t)\phi_{fn}^*(t)$: **short-time Fourier transform (STFT)** of temporal signal $x(t)$.
- ▶ $s_{fn} = |y_{fn}|^2$: **power spectrogram**.
- ▶ NMF extracts **recurring spectral patterns** from the data by solving

$$\min_{\mathbf{W}, \mathbf{H} \geq 0} D(\mathbf{S} | \mathbf{W}\mathbf{H}).$$

- ▶ Successful applications in **audio source separation** and **music transcription**.

Itakura-Saito NMF & the Gaussian composite model

(Févotte, Bertin, and Durrieu, 2009)

- ▶ Low-rank variance model of **analysis coefficients** (STFT):

$$y_{fn} \sim N_c(0, [\mathbf{WH}]_{fn}).$$

- ▶ Log-likelihood equivalent to **Itakura-Saito (IS) divergence**:

$$-\log p(\mathbf{Y}|\mathbf{WH}) = D_{\text{IS}}(|\mathbf{Y}|^2|\mathbf{WH}) + \text{cst.}$$

- ▶ Underlies a **Gaussian composite model (GCM)**:

$$y_{fn} = \sum_k y_{kfn},$$

$$y_{kfn} \sim N_c(0, w_{fk} h_{kn}).$$

- ▶ Given estimates of **W** and **H**, latent STFT components can be estimated by **Wiener filter**:

$$\hat{y}_{kfn} = \frac{w_{fk} h_{kn}}{[\mathbf{WH}]_{fn}} y_{fn}.$$

- ▶ **Inverse-STFT** of $\{\hat{y}_{kfn}\}_{fn}$ produces **temporal components** such that $x(t) = \sum_k \hat{c}_k(t)$.

Low-rank time frequency synthesis (LRTFS)

(Févotte and Kowalski, 2014)

- ▶ Low-rank variance model of **synthesis coefficients**:

$$x(t) = \sum_{fn} \alpha_{fn} \phi_{fn}(t) + e(t),$$

$$\alpha_{fn} \sim N_c(0, [\mathbf{WH}]_{fn}),$$

$$e(t) \sim N_c(0, \lambda).$$

- ▶ $\phi_{fn}(t)$: **time-frequency atom** (e.g., from a Gabor frame),
- ▶ α_{fn} : **synthesis coefficient**,
- ▶ $e(t)$: **residual term**.
- ▶ **LRTFS is a generative model of raw data $x(t)$** .
- ▶ Like in the GCM, the synthesis coefficients have a **latent composite structure**:

$$\alpha_{fn} = \sum_k \alpha_{kfn},$$

$$\alpha_{kfn} \sim N_c(0, w_{fk} h_{kn}).$$

- ▶ Given estimates of **W** of **H**, latent coefficients α_{kfn} can be estimated from their posterior mean and **temporal components** can be reconstructed as $\hat{c}_k(t) = \sum_{fn} \hat{\alpha}_{kfn} \phi_{fn}(t)$.

Relation to sparse Bayesian learning (SBL)

- ▶ Generative signal model in vector/matrix form:

$$\mathbf{x} = \mathbf{\Phi}\boldsymbol{\alpha} + \mathbf{e}.$$

- ▶ \mathbf{x} , \mathbf{e} : vectors of **signal and residual time samples** (size T),
 - ▶ $\boldsymbol{\alpha}$: vector of **synthesis coefficients** α_{fn} (size FN),
 - ▶ $\mathbf{\Phi}$: **time-frequency dictionary** (size $T \times FN$).
- ▶ Synthesis coefficients model in vector/matrix form:

$$p(\boldsymbol{\alpha}|\mathbf{v}) = N_c(\boldsymbol{\alpha}|\mathbf{0}, \text{diag}(\mathbf{v})).$$

- ▶ \mathbf{v} : vector of **variance coefficients** $v_{fn} = [\mathbf{WH}]_{fn}$ (size FN).
- ▶ Similar to **sparse Bayesian learning** (Tipping, 2001; Wipf and Rao, 2004) except that the **variance parameters are tied together** by the low-rank structure **WH**.

Estimation in LRTFS

Maximum joint likelihood (JL)

- ▶ Optimise

$$\begin{aligned} C_{\text{JL}}(\boldsymbol{\alpha}, \mathbf{W}, \mathbf{H}, \lambda) &\stackrel{\text{def}}{=} -\log p(\mathbf{x}, \boldsymbol{\alpha} | \mathbf{W}, \mathbf{H}, \lambda) \\ &= \frac{1}{\lambda} \|\mathbf{x} - \boldsymbol{\Phi}\boldsymbol{\alpha}\|_2^2 + D_{\text{IS}}(|\boldsymbol{\alpha}|^2 | \mathbf{v}) + \log(|\boldsymbol{\alpha}|^2) + \text{cst.} \end{aligned}$$

- ▶ Possible EM algorithm using the procedure of (Figueiredo and Nowak, 2003) based on the **hidden variable \mathbf{z}** such that

$$\begin{aligned} \mathbf{x} &= \boldsymbol{\Phi}\mathbf{z} + \mathbf{e}_1, \\ \mathbf{z} &= \boldsymbol{\alpha} + \sqrt{\beta} \mathbf{e}_2, \end{aligned}$$

with $\mathbf{e}_1 \sim N_c(\mathbf{0}, \lambda \mathbf{I} - \beta \boldsymbol{\Phi}\boldsymbol{\Phi}^*)$ and $\mathbf{e}_2 \sim N_c(\mathbf{0}, \mathbf{I})$ (condition applies on β).

- ▶ Leads to a form of **iterative shrinkage algorithm** that scales well with **real-world signal dimension**.

Shrinkage operator involves **Itakura-Saito NMF of power posterior expectation of $\boldsymbol{\alpha}$** at each iteration.

Estimation in LRTFS

Maximum marginal likelihood (ML)

- ▶ Integration of α from the joint likelihood (like in SBL)

$$\begin{aligned} C_{\text{ML}}(\mathbf{W}, \mathbf{H}, \lambda) &\stackrel{\text{def}}{=} -\log p(\mathbf{x}|\mathbf{W}, \mathbf{H}, \lambda) \\ &= -\log \int_{\alpha} p(\mathbf{x}|\alpha, \lambda) p(\alpha|\mathbf{W}\mathbf{H}) d\alpha \end{aligned}$$

- ▶ Possible EM algorithm treating α as the hidden variable.
Tractable algorithm but does not scale well with dimension.

Toy example



(MIDI numbers : 61, 65, 68, 72)

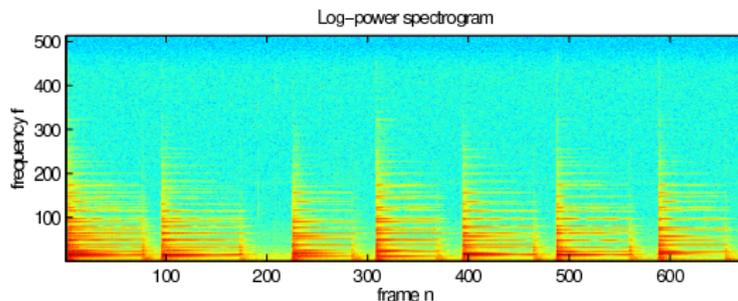
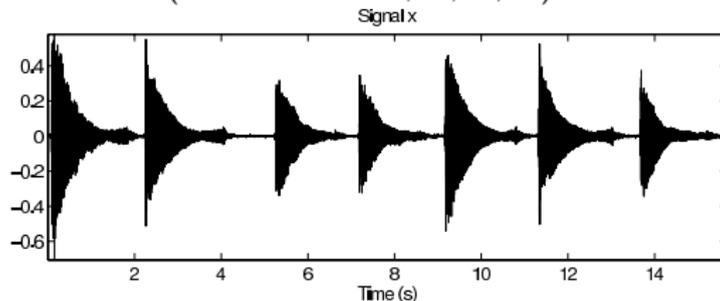
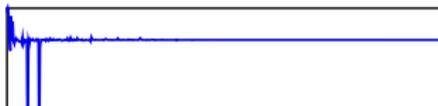
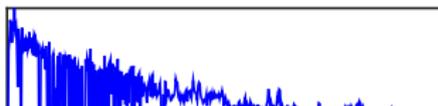
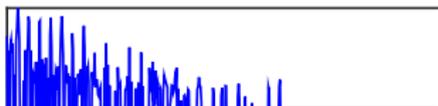
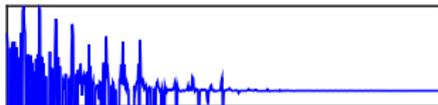
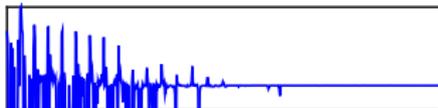


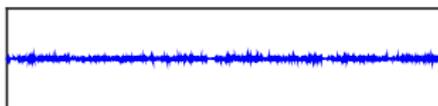
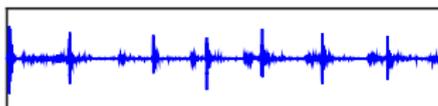
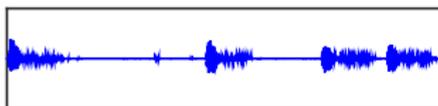
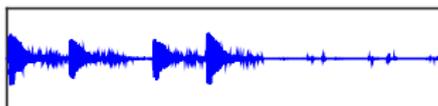
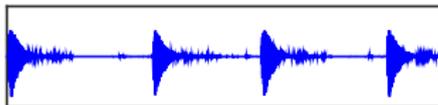
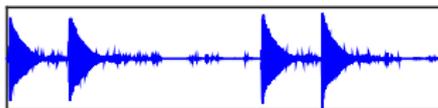
Figure: Three representations of data.

Toy example

Dictionary \mathbf{W}



Reconstructed components



Multi-resolution LRTFS

- ▶ LRTFS allows for multi-resolution hybrid representations:

$$\mathbf{x} = \mathbf{\Phi}_a \boldsymbol{\alpha}_a + \mathbf{\Phi}_b \boldsymbol{\alpha}_b + \mathbf{e}.$$

- ▶ $\mathbf{\Phi}_a$ and $\mathbf{\Phi}_b$ are time-frequency dictionaries with different resolutions,
 - ▶ $\boldsymbol{\alpha}_a$ and $\boldsymbol{\alpha}_b$ have their own latent low-rank structure $\mathbf{W}_a \mathbf{H}_a$ and $\mathbf{W}_b \mathbf{H}_b$.
- ▶ Not possible with standard NMF !
 - ▶ Previous optimisation strategies apply by concatenation:

$$\mathbf{\Phi} = [\mathbf{\Phi}_a \ \mathbf{\Phi}_b]$$

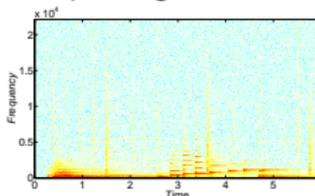
$$\boldsymbol{\alpha} = \begin{bmatrix} \boldsymbol{\alpha}_a \\ \boldsymbol{\alpha}_b \end{bmatrix}$$

- ▶ Other hybrid decompositions are possible.
E.g., low-rank layer + sparse layer (forthcoming EUSIPCO paper)

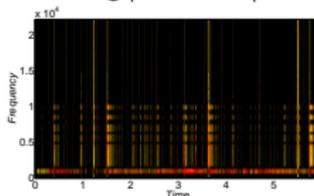
Hybrid decomposition of jazz music

$$\mathbf{x} = \Phi_{\text{tonal}} \alpha_{\text{tonal}} + \Phi_{\text{transient}} \alpha_{\text{transient}} + \mathbf{e}$$

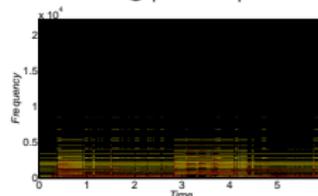
spectrogram of \mathbf{x}



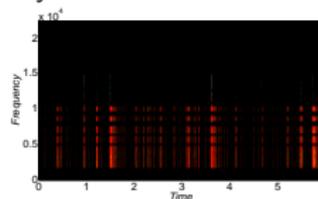
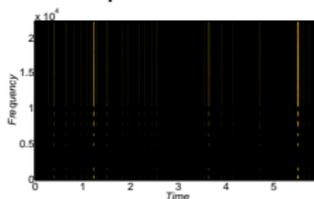
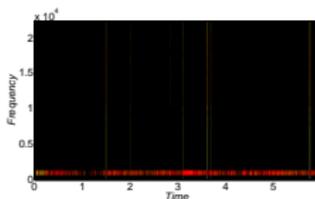
$\log |\hat{\alpha}_{\text{transient}}|$



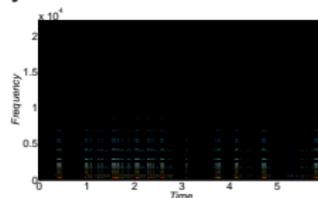
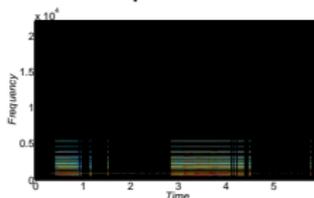
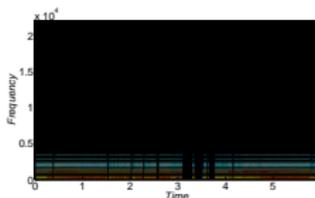
$\log |\hat{\alpha}_{\text{tonal}}|$



Latent rank-1 components from transient layer



Latent rank-1 components from tonal layer

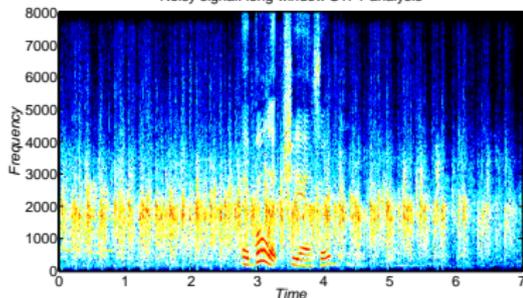


Speech enhancement in applause noise

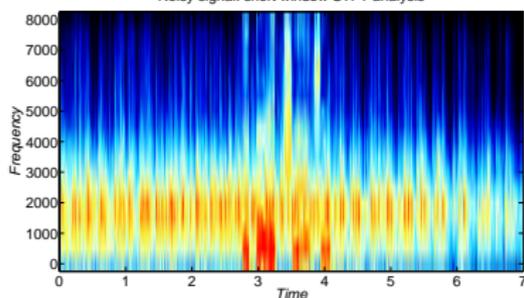
$$\mathbf{x} = \Phi_{\text{tonal}} \left(\alpha_{\text{tonal}}^{\text{speech}} + \alpha_{\text{tonal}}^{\text{noise}} \right) + \Phi_{\text{transient}} \left(\alpha_{\text{transient}}^{\text{speech}} + \alpha_{\text{transient}}^{\text{noise}} \right) + \mathbf{e}$$

Spectrograms of x with short and large resolutions

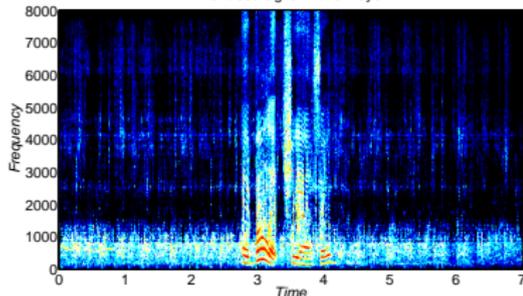
Noisy signal: long window STFT analysis



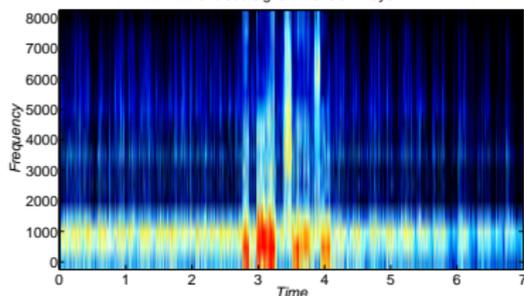
Noisy signal: short window STFT analysis



$\log |\hat{\alpha}_{\text{tonal}}^{\text{speech}}|$
Denoised signal: Tonal Layer



$\log |\hat{\alpha}_{\text{transient}}^{\text{speech}}|$
Denoised signal: Transient Layer



A dedication to Bill Fitzgerald



Prof. William J. Fitzgerald (1948-2014)

AN INTRODUCTION TO
BAYESIAN INFERENCE APPLIED TO SIGNAL AND DATA
PROCESSING

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16/5/2001

(my first tutorial on Bayesian inference)

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